



dSPACE: Digital Signal Processing And Control Engineering

Distributors in

More than

family-owned company; visionary founder

countries

years of experience

>2.000

global employees

Local dSPACE companies in

countries around the globe

Project centers in

4

german cities

~1.600
engineers and software scientists

Continuously growing R&D and engineering capacities and capabilities, investing in state-of-the-art technology





Solutions for Electromobility

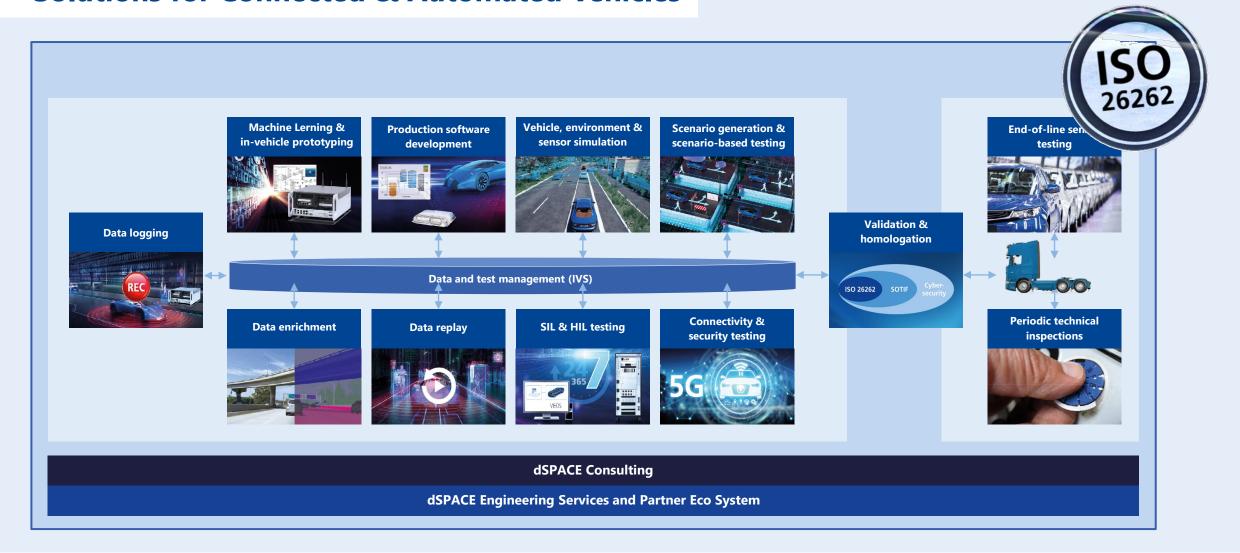
Combining electric vehicles and renewable energy sources are mega trends for modern mobility.



Smart Grids, Charging, Energy Storage, Power Electronics, Electric Drives, PLC, 4G, 5G, WiFi, GNSS



Solutions for Connected & Automated Vehicles





Connectivity in Ground Vehicles

Application type	Use Case	Communication type
Infotainment	In-car entertainment & internet access	4G/5G
Infotainment	In-car voice assistant (Alexa, Siri, Google Assistant)	4G/5G
Smart Mobility	Community/Smart Parking, Carsharing, MaaS	4G/5G
Safety	eCall/NG eCall	2G/4G
Safety/Efficiency	Remote diagnostics	4G/WLAN
Efficiency	Predictive driving (eHorizon, Live HD maps)	4G/5G
Comfort	Keyless Entry	4G/BT/UWB
Safety	V2X Day One (safety applications)	V2X (V2V, V2I)
Comfort	Automated Valet Parking/Remote Parking	WLAN/BT
Safety/Comfort/Efficiency	OTA Update for Software-defined Vehicle	4G/WLAN
Comfort/Efficiency	Traffic Light Information, GLOSA	4G/V2I
Comfort/Efficiency	Cooperative ACC	V2X
Safety/Efficiency	Platooning	V2X
Safety	Sensor Sharing	V2X/5G
Safety	VRU Protection	V2X/5G
Safety/Efficiency	Cooperative Maneuvering/Driving	V2X/5G
Safety/Comfort/Efficiency	L4/L5 self-driving cars	V2X/5G

Increasing demand for advanced simulation & testing



V2P: Vehicle-to-Pedestrian BT: Bluetooth MaaS: Mobility-as-a-Service UWB: Ultra-wideband GLOSA: Green Light Optimized Speed Advisory



Roadmap towards CAV

Semiautomated Driving

V2X Day 3+

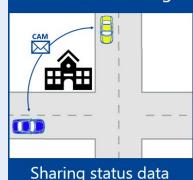
Fullyautomated Driving

Driver **Assistance**



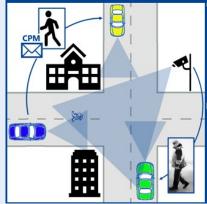
V2X Day 1

Awareness Driving Collision Warning



Simple use cases for driver information

Collective Perception VRU protection



Sharing object list

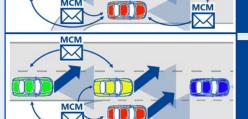
V2X Day 2

Sharing sensor raw data 5Ĝ

Integration with functions for perception and data fusion

Need for Sensor Simulation Need for Infrastructure Simulation **Cooperative Driving**





Sharing intention

Maneuver coordination 5Ĝ

Integration with functions for maneuver planning and decision making

Need for Scenario-based Testing **Need for Large Scale Simulation**

Increasing number and complexity of scenarios Increasing demand for simulation and validation



Connected

Automated

Vehicle

Vision for smart mobility and connected autonomous vehicle

- Smart parking
- Carsharing
- MaaS

LTE/5G

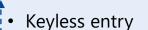
- Smart charging
- Wireless BMS



- eHorizon
- Live HD maps
- Traffic light information
- GLOSA
- Sensor sharing
- VRU protection
- Automated driving







Remote parking V2P :

VRU protection <

Connected Services

(6



•••

Backend

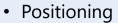
- Video/Gaming
- Internet access
- Voice assistance
- eCall
- Predictive driving
- Remote diagnostics
- OTA update/software-defined vehicle





- Emergency vehicle warning
- Inersection collision warning
- Cooperative ACC
- Platooning
- Cooperative driving
- Automated driving





• Time



MAP = Road topology **V2X Day1: Infrastructure Simulation** Nodes' Create or import 19 roads from Lanes OpenStreetMap, OpenDrive, Connections TomTom, HERE, ... SignalGroup **MovementState** Define signal timing plan SPAT = Signal Phase & Timing MovementEvent AdvisorySpeeds MaxEndTime State (e.g. stop+remain) Use Case: Simulation provides content Traffic Light for complex MAP & SPaT Information



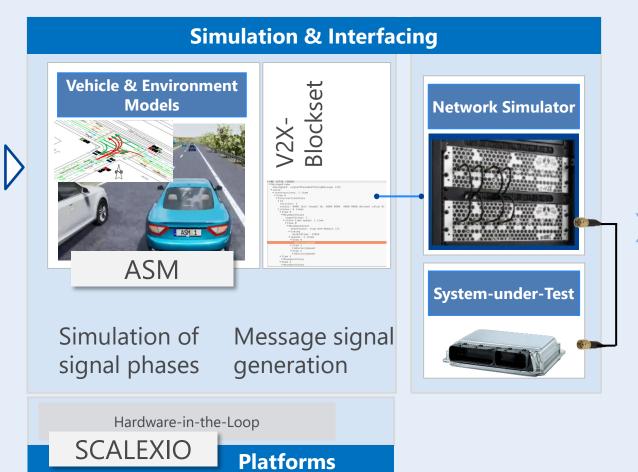


GLOSA...

V2X – MAP and SPaT

Parameterization and simulation of map data and signal phases

Preparation Scenario Editor & Parameterization ModelDesk Definition of signal phases and timing



Key takeaways

V2X signal definition in ModelDesk

V2X MAP and SPaT (Signal phase and timing) **simulation** in ASM

V2X MAP and SPaT message generation with V2X-blockset



V2X Day 2: Collective Perception

Challenges for Testing

- Sensors simulation with different levels of detail
- Multiple, different sensors and sensor fusion
- Environment simulation with pedestrians, cyclists, construction zones, etc.
- Sensor-realistic Simulation and 5G emulation for HD Sensor Sharing...

Collective Perception Message
(CPM)

ITS PDU Header

Management Container

Station Data Container

Sensor Information Container

Perceived Object Container

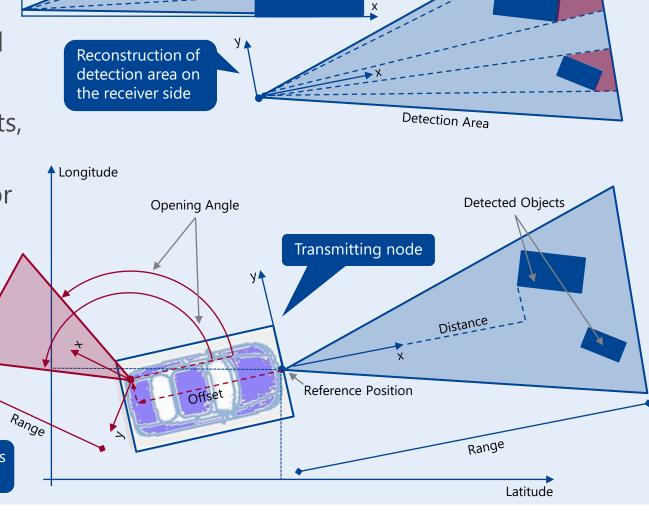
Distance, Type,
Dimensions...

Free Space Addendum Container

Reference Position,
Station Type...

Mounting Position,
Range, Opening
Angels...

Free space confidence levels
within detection area



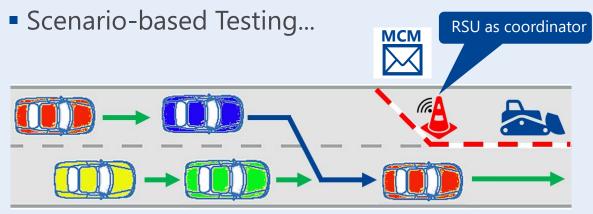
Detection Area

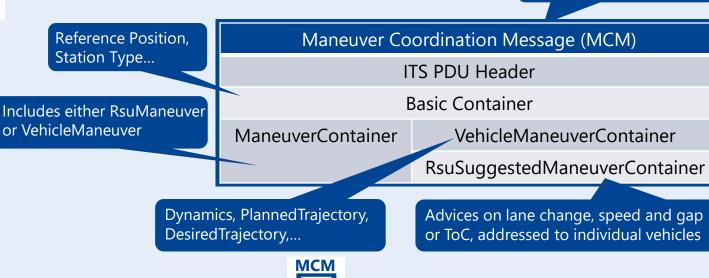


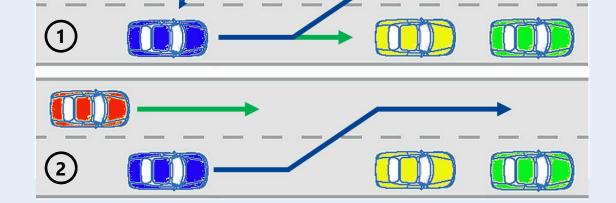
Shadowed Area

Challenges for Testing

- Lots of different scenarios
- Varying number of vehicles
- Trajectory simulation
- Infrastructure simulation with support of maneuver coordination



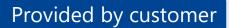






Testing 4/5G-enabled services & Handover





Data link

Data link control

Trigger realistic handover

Manipulate data throughput

Control BS signal power

Manipulate data link quality...





TCU Testing



Conducted or via antenna

5G/4G Radio Access Network Simulation

Access to Edge Computing/Cloud

Core Network Simulation

Mobile Network Simulator

5G Base station and Core

envision: ensure

Sensor Realistic Simulation

V2Cloud Control Interface



Real-time simulator

Restbus simulation (Ego positions, speed, ...)

TCU: Telematics Control Unit (Connectivity device)

BS: Base Station

(e)SIM: (embedded) Subscriber Identity Module ASM: dSPACE Automotive Simulation Models





Vehicle

bus







GNSS signal generator

Device Under Test

Simulation and test control





GNSS signal

Source: Spectracom Telematics Control Unit



Vehicle bus

(CAN...)

Real-time simulation



(TCP/IP)

SCPI via Ethernet

GNSS Simulator Interface Blockset

- Select GNSS scenarios
- Set date and start time
- Provide EGO positions (latitude, longitude, altitude)
- Control TX power
- Receive status information

Rest bus simulation

eHorizon, V2X, AD...

RF

Road Import from OpenStreetMap, Google, TomTom, HERE, GPS...







Supports standardized
 V2X application protocols

 Easy integration, also with existing test environment V2X simulation



V2X related data

All standards: EU, US, CN





Dynamic channel attenuation and load generation

Supports secured communication

Device Under Test

V2X messages RF V2X ECU

GPS RF

V2X Interface GNSS Interface Position of EGO vehicle



II SAUSO VEOS

Reduce workload with

- Scenario Generation
- Scenario-based Testing



Different satellite constellations, locations all over the world

Sensors models for testing Collective Perception

Infrastructure simulation to master complexity of V2I scenarios

Rest bus simulation









Integrated ADAS/AD Sensor Testing

"Virtual vehicle" system for SW verification in labs



Key takeaways

Comprehensive portfolio

Over-The-Air stimulation and data injection of

- Radar
- Lidar
- Camera
- Ultrasonic

automotive sensors plus

- GNSS
- V2X

Traffic model by dSPACE ASM.

dSPACE offers complete, integrated ADAS testing systems from one source!



VIL for AD – Vehicle OTA Testing

Integrated Vehicle-in-the-loop test setup



Key takeaways

Combine Over-The-Air stimulation of

- Radar
- Camera
- Ultrasonic
- GNSS
- V2X

Synchronous stimulation of all sensors!



